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# SIFB set for accessing Beckhoff controllers using ADS protocol

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# Introduction

- Introduction
- TwinCAT System
- TwinCAT ADS
- 4DIAC-ADS
- Case Study
- Summary

- **4DIAC/FORTE IEC 61499 environment for distributed control systems development**
- **4DIAC need drivers** to access industrial control systems
- **Beckhoff TwinCAT ADS** (Automation Device Specification) messaging protocol allows a wide and easy IO realtime data access

# Introduction

● Introduction

TwinCAT System

TwinCAT ADS

4DIAC-ADS

Case Study

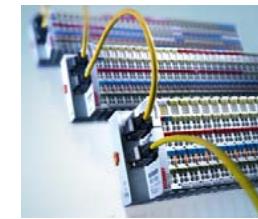
Summary

## Beckhoff

*The IPC Company*



*The I/O Company*



**BECKHOFF**

Beckhoff implements open automation  
systems based on PC Control technology

*The Motion Company*



*The Automation Company*



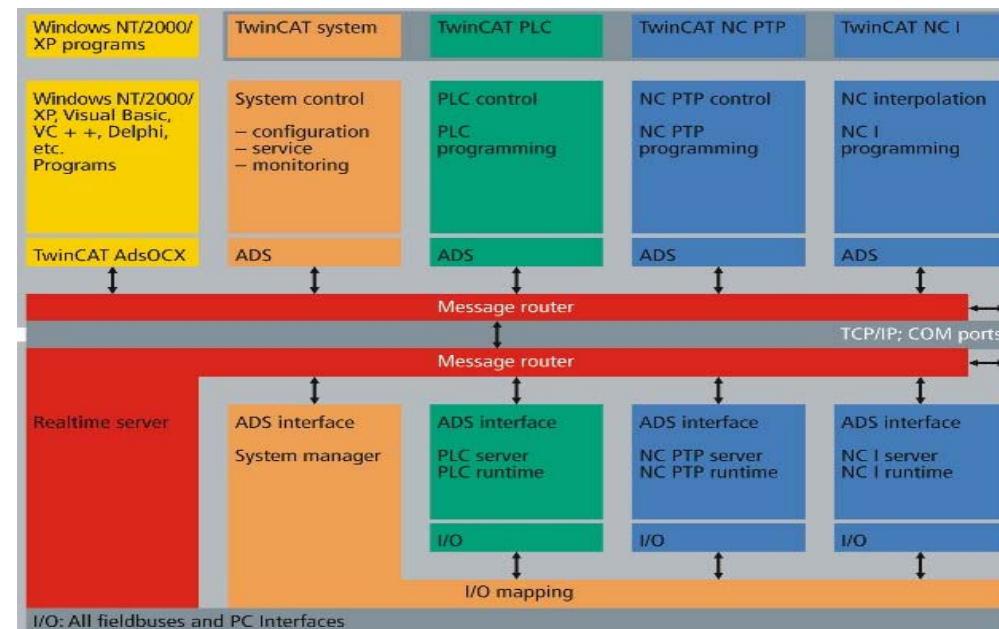
# TwinCAT System

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**TwinCAT is an automation package comprising engineering and runtime software for:**

- motion (Software Motion Control)
- technological function (controllers, communication, OS functions, etc...)

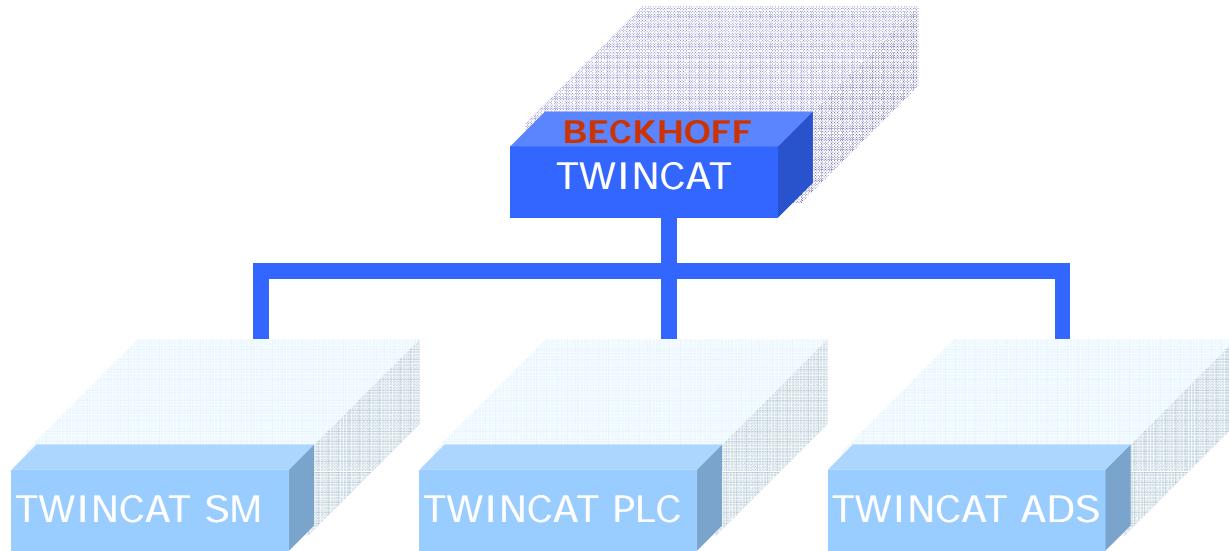
and all this in HARD REALTIME on Windows NT/2000/XP  
as well as on Windows NT/XP Embedded and CE.NET



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- Sequence control (Software PLC)
- **communication over all components (ADS)**

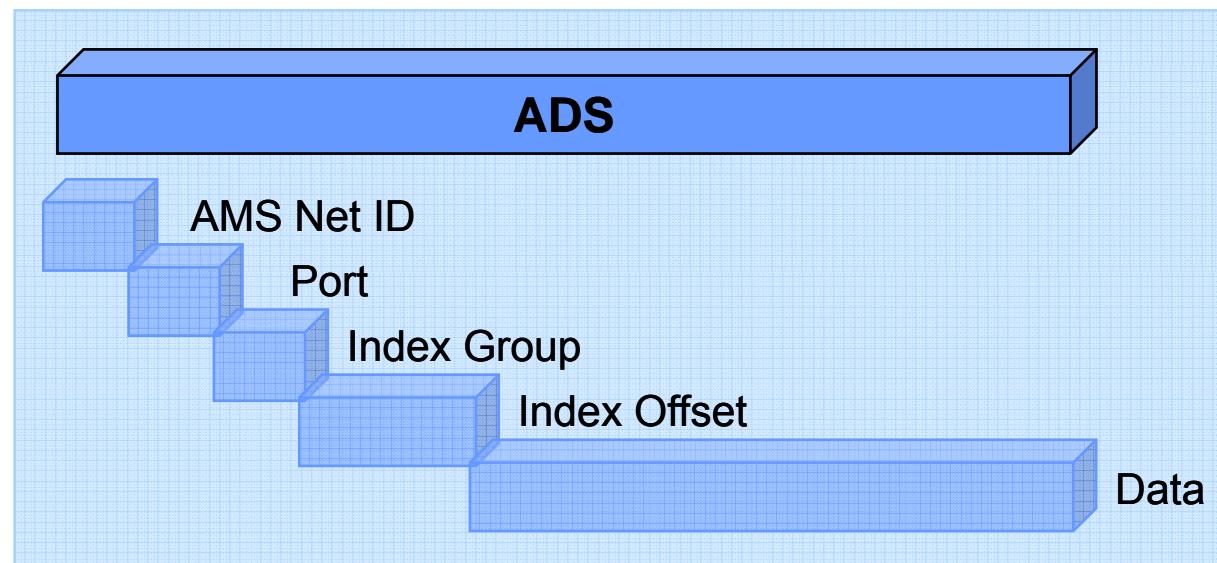


- Is the configuration center for the system:
- **The TwinCAT ADS Communication Library** organizes data communication between the PLC and Windows programs and includes independently of the manufacturer
  - **Configuration of I/O channels**
  - **Connects I/O devices to tasks** in a variable-oriented manner
  - Use to all defined programming languages: IL, FBD, LD, SFC, ST
  - Connects tasks to tasks in a variable-oriented manner
  - Has a powerful development environment for programs
  - Supports units at the bit level what exceed the capacities of conventional PLC systems
  - **Supports synchronous or asynchronous relationships**
  - Exchange of consistent data areas and process images

# TwinCAT ADS Protocol

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- ❑ **ADS protocol, is a transport protocol** within the Beckhoff TwinCAT system
- ❑ Developed for data exchange between the different software modules
- ❑ Offers the freedom of using other tools to communicate
- ❑ Is used on top of TCP/IP
- ❑ All the data is accessible from any desired point



# TwinCAT ADS Properties

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## ADS Properties

- **ADS describes a device independent** and fieldbus independent interface **governing the type of access** to ADS devices
- **ADS enabled devices** - PC running TwinCAT, Beckhoff BC Bus Controllers
- **I/O data** are imported via ADS and are **mapped to the device**
- This greatly **reduces programming time**



TWINCAT ADS

# TwinCAT ADS Properties

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## ADS properties

- ADS enables applications **to communicate** to fieldbus devices in **cyclic and acyclic way**
- This protocol enables a wide range of communication and **enables local and remote access**
- An **ADS address** (AMS Net ID) is **configured** to devices using **acyclic communication**
- ADS allows **horizontal and vertical** application-to-application **communication** throughout several platforms (Windows NT/CE, TCP/IP, fieldbuses)



TWINCAT ADS

# TwinCAT ADS Device

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**ADS Device is an object that implements the ADS interface and offers “ADS server services”**

- Real-time communication to Input/Output devices
- ADS handles streamed data through **synchronous and asynchronous** communication support
- ADS **access all devices** through IP type addresses
- The TwinCAT message router **distributes messages** based on **TCP/IP** over wide system



TWINCAT ADS

# TwinCAT ADS Architecture

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## ADS Client/Server Architecture

- Beckhoff system allows individual software modules **as independent devices**
- Any task can performs a software module (Server or Client)
- Servers are implemented like software devices which operate like traditional hardware devices
  - **Server works** like "virtual devices" implemented by software
- Clients are programs which request services from servers



TWINCAT ADS

# TwinCAT ADS Access

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**TwinCAT ADS organizes the exchange of data between TwinCAT and Windows programs and includes:**

- Searching for variables
- Access by variable name
- Synchronization of timing with the operating system
- Adaptation of the differing data types
- Creation of data blocks and list generation to improve System effectiveness
- Ensuring that accessed data are consistent

**Access methods**

- Synchronous: cyclic
- Asynchronous: notify on change

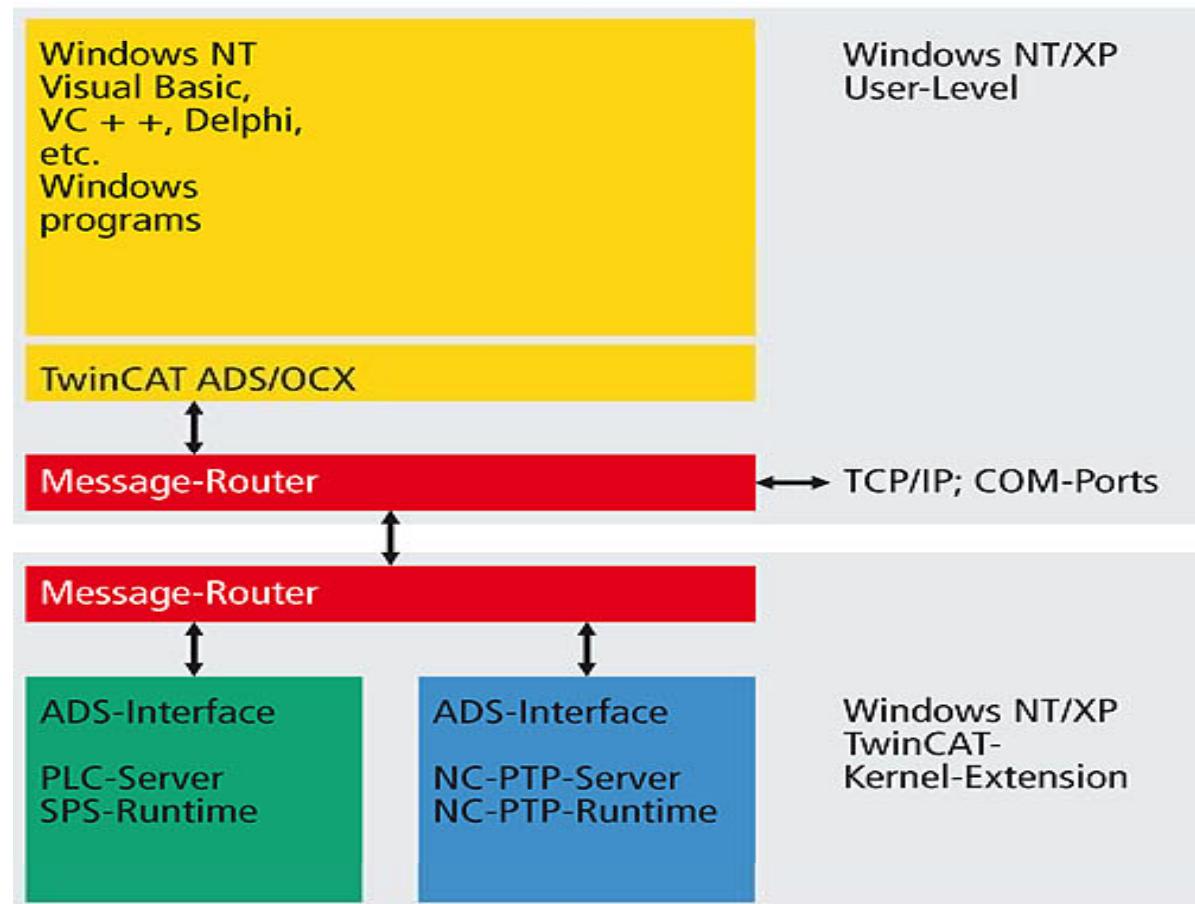


TWINCAT ADS

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The data link to TwinCAT servers is performed via the message system



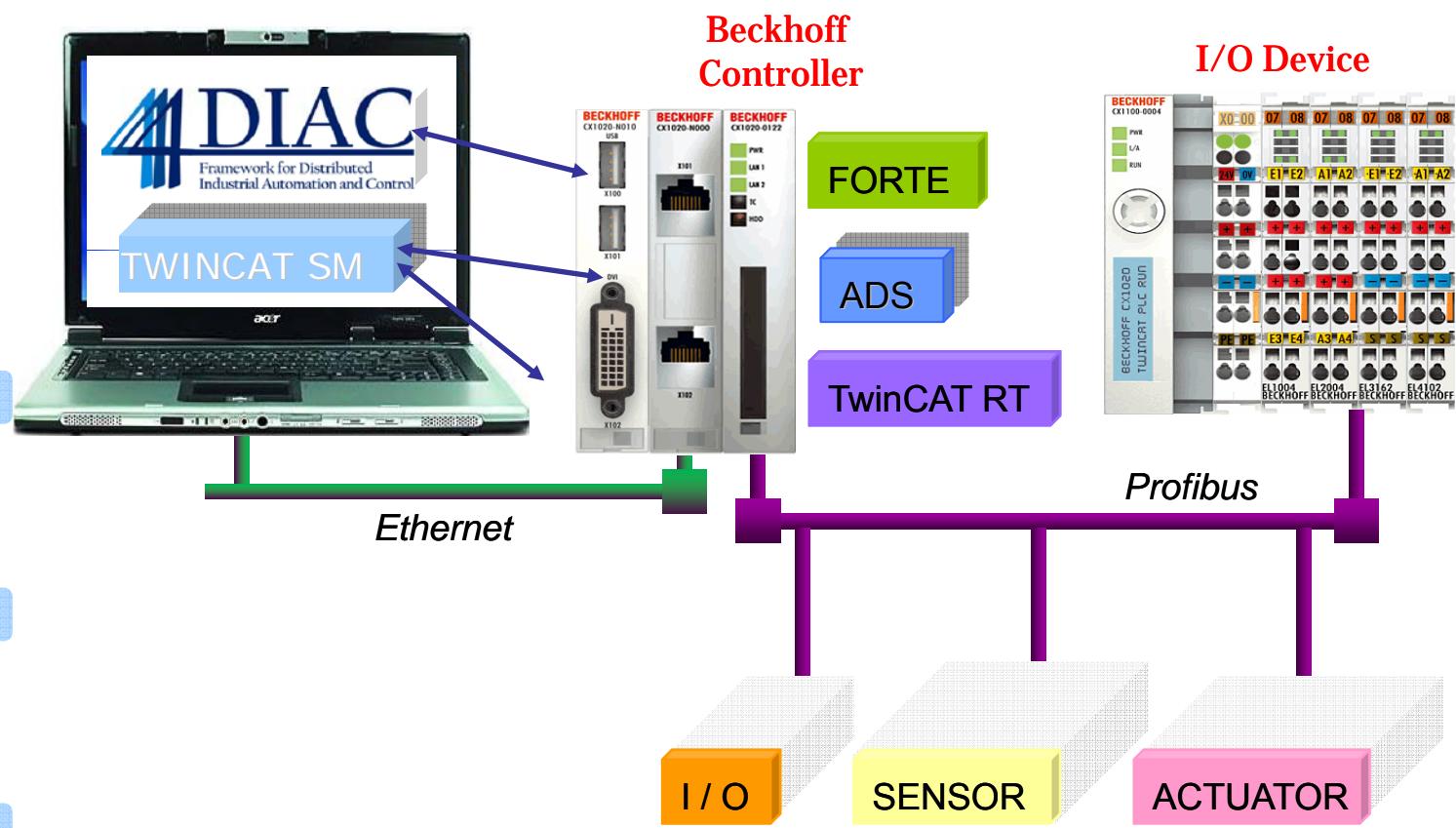
# TwinCAT ADS Communication Library

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- TwinCAT Communication Library is a collection of ADS components
  - The **ADS library** is included in the full TwinCAT software, but it is also available as a free, **separate package from Beckhoff**
  - Organizes data exchange between TwinCAT and Windows programs and includes the search for variables
  - The TwinCAT interface for **programming languages** (Visual Basic, Visual **C/C++**, Delphi, Java, ...)
  - **ADS data exchange** can be managed transparently via different **physical transport** routes: TCP, UDP, **fieldbus**, EtherCAT, serial, SOAP
  - **ADS components** are available for the following areas of implementation: **DLL**, OCX, VB Script, J Script, .NET assembly, Java, web service
  - **ADS DLL**: It's possible to link the **ADS DLL (Dynamic Link Library)** into one **C/C++ program**

# 4DIAC-ADS Functional System

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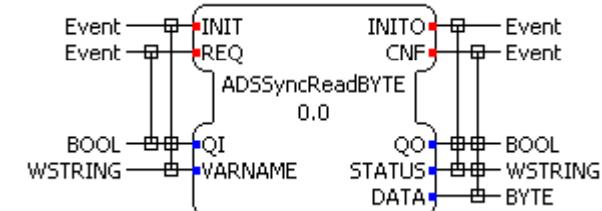
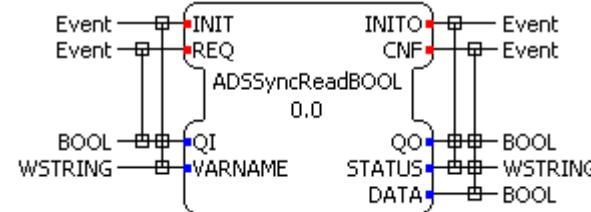
# 4DIAC SIFBs set for ADS

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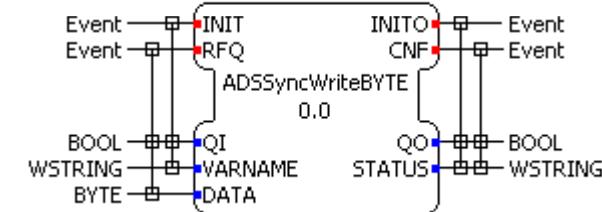
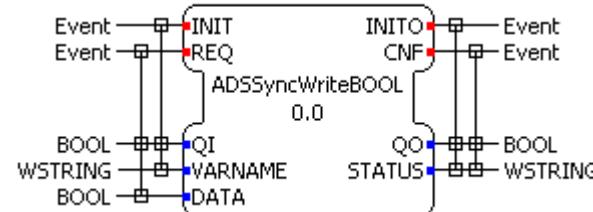
## SIFBs set elements

- Synchronous Read/Write for real time control data

### ✓ SIFBs ADSSyncReadBOOL and ADSSyncReadByte



### ✓ SIFBs ADSSyncWriteBOOL and ADSSyncWriteByte



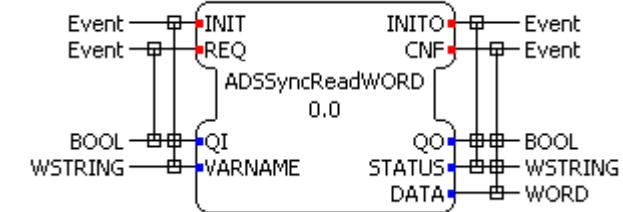
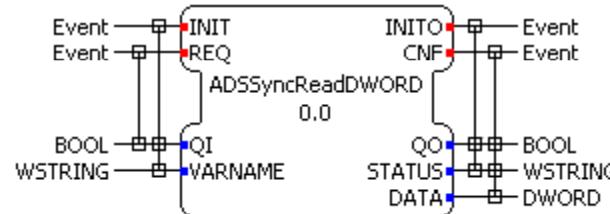
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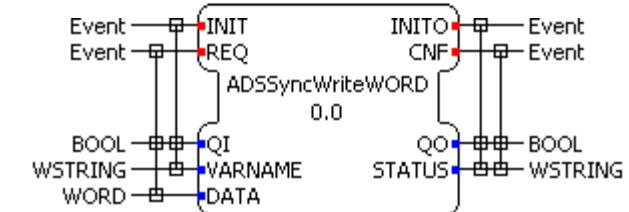
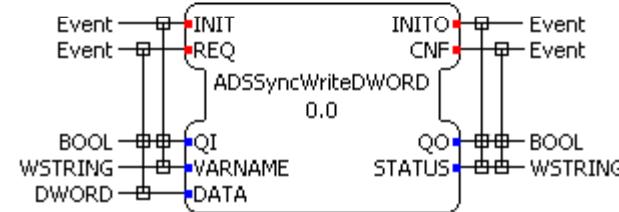
## SIFBs set elements

- Synchronous Read/Write for real time control data

### ✓ SIFBs ADSSyncReadDWORD and ADSSyncReadWORD



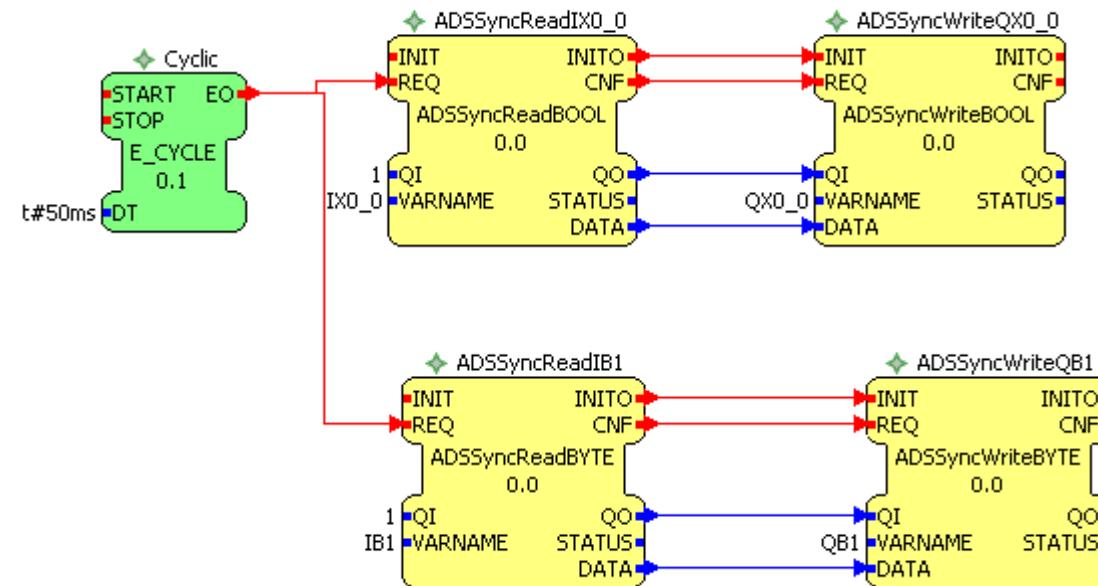
### ✓ SIFBs ADSSyncWriteBOOL and ADSSyncWriteByte



# ADS Application

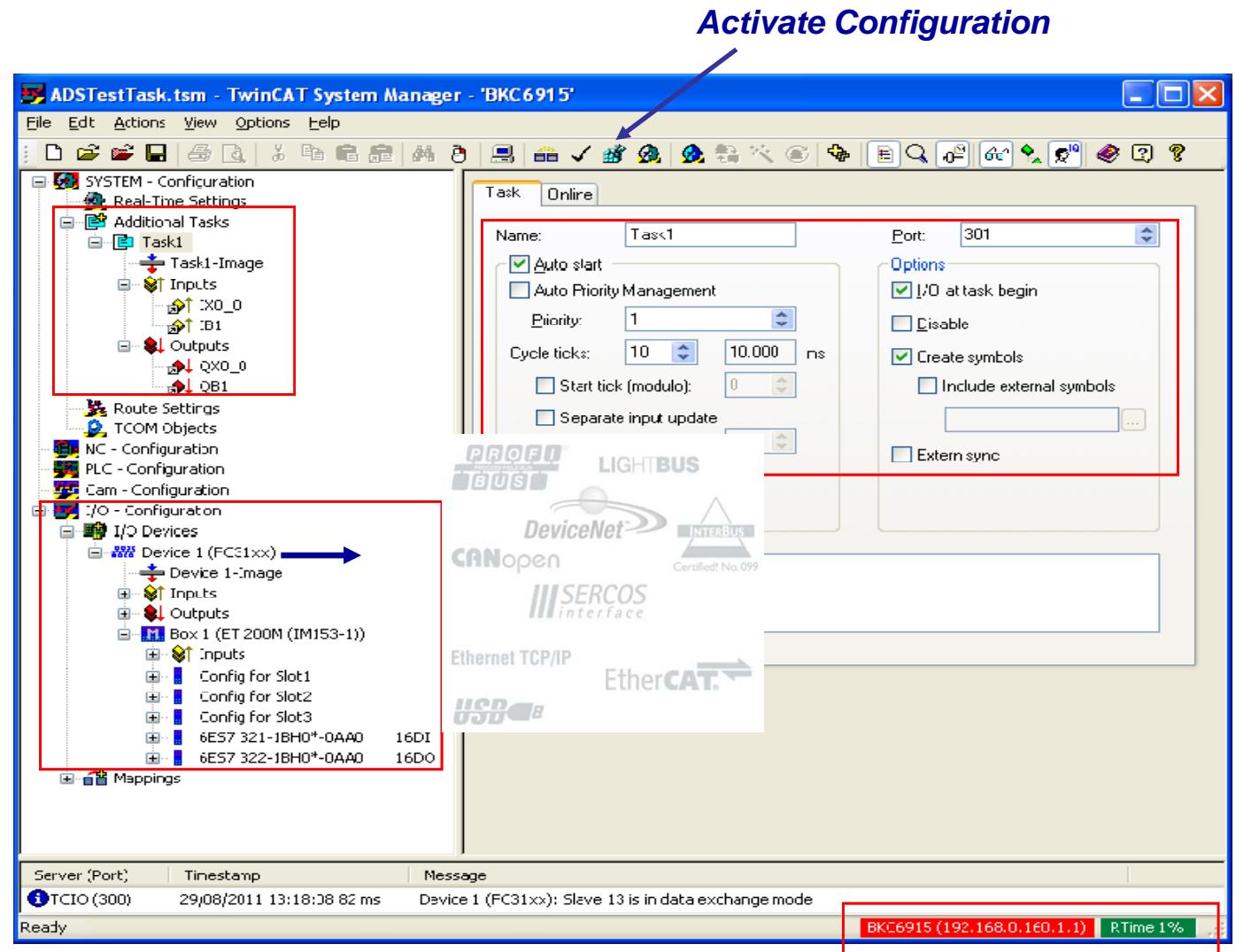
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## An Easy Application



# TwinCAT SM Configuration

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# Case Study

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## Test platform

Programming,  
Configuration  
and Commis



# Summary

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- ❑ **ADS** enables a common protocol for **accessing IO data** in Beckhoff controllers
  - Direct IO interfaces: K-bus, E-bus
  - Fieldbus interfaces: **Profibus**, Interbus, CANopen, DeviceNet, Ethernet, EtherCAT, Sercos, ...
- ❑ Beckhoff TwinCAT SM **enables hardware/IO data configuration**
- ❑ 4DIAC SIFBs set for **local variables access** using ADS
- ❑ **IEC 61499 4DIAC applications close to Industrial Control**

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**Thank you for your  
attention!**